

ABSTRACT OF THE DISCLOSURE

In a rendering device *Urnd1*, a processor 1 derives an estimated path to be traced by a left- and right-rear wheels of a vehicle based on a rudder angle θ provided by a rudder angle sensor 5. The processor 1 then determines positions for overlaying indicators on the derived estimated path. The processor 1 then renders the indicators on thus determined points in a captured image provided by an image capture device, and generates a display image. Here, in the display image, the indicators move along the estimated path in the heading direction of the vehicle. In this manner, the estimated path in the display image generated by the rendering device *Urnd1* becomes noticeable for a driver of the vehicle.

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